

LS-DYNA PDB WorldSID 50th V3.0 release notes

A. Gromer DYNAmore GmbH, Germany Stuttgart, 28. February 2014



outline

- Geometric modifications
- component tests
- Further modifications
- New positioning procedure

for more detailed information refer to the dummy model manual



New jacket mesh

- Neoprene jacket meshed with hexa/penta elements
- Impact side refined





Modified arm mesh

- Hyperlast rubber foam mesh is now disconnected from arm bone
- Better correlation with initial slope of shoulder force





corrected rib damping material geometry

- Same length but panned to the outer bracket
- All ribs were modified





Inner pelvis assembly of WorldSID SBL-E1

- New data recorder box
- Data recorder plug replacement removed





Stuttgart, 28. February 2014

component tests

MORE

0 0

Component tests

- New shoulder rib z-direction pendulum test (vertical)
- New shoulder rib test with arm
- Neck and arm validation improved on component level



Further modifications to address users requests

- The nitinol material of the rib bands now uses am *MAT_SHAPE_MEMORY. This should increase the overall stability and robustness of the dummy model
- 2D IR-TRACCs are modeled by beams. It is now possible to extract the rib deflection and the corresponding rib rotation. The evaluation of the 1D IR-TRACCs still exists.
- Some load cell orientations were corrected to match the SAE standard: upper and lower neck, shoulder, lumbar spine, pubic, sacro iliac and femur load cells
- Improvement of the pelvis flesh model to avoid high hourglass energies
- Improvement of the hole dummy definitions to reduce time step dependency of the model
- Parameter tpref to switch on/off the foam reference geometry of the thorax pad



New positioning procedure

- Main goal: simplify the positioning of the WorldSID 50th
- 1. Generate your target procedure in your preprocessor. Do not worry about penetrations, Save it as a normal key file.





Stuttgart, 28. February 2014

New positioning procedure

2. Run the script which is enclosed in your delivery package.

psg_wsid50_v3.0 -d dummyinput_origin.key -t target_pos_dummy.key

The script generate an positioning simulation file dummyinput_origin_positioning.key

3. Run the input in dummyinput_origin_positioning.key LS-DYNA (recommended version R6.1.2) final

4. Setup the positioned dummy model with the nodal coordinates of the last state of the positioning run.



